

Microeconometrics: Clustering

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1 Gauss Markov Assumptions

- OLS is minimum variance unbiased (MVUE) if
 - Linear Model: $Y_i = X_i\beta + \epsilon_i$
 - $E(\epsilon_i|X_i) = 0$
 - $V(\epsilon_i|X_i) = \sigma^2 < \infty$
 - $cov(\epsilon_i, \epsilon_j) = 0$
 - Normally distributed errors.
- What happens if we relax homoskedasticity? Uncorrelated errors?
 - Bias of $\hat{\beta}$? No!
 - Bias of $SE(\hat{\beta})$?
 - * Yes, distorted test size: OLS formula for standard errors not valid: $\sigma^2 (X'X)^{-1}$

* Up or down? Could be either (In general, positive correlation \implies OLS standard errors are too low, negative correlation \implies OLS standard errors are too high).

– OLS not MVUE anymore

- This lecture will be about what to do when the homoskedasticity and uncorrelated errors assumptions are relaxed

2 Non-Spherical Disturbances: Examples

2.1 Classical OLS

$$\begin{pmatrix} \sigma^2 & 0 & 0 & 0 & 0 \\ 0 & \sigma^2 & 0 & 0 & 0 \\ 0 & 0 & \sigma^2 & 0 & 0 \\ 0 & 0 & 0 & \sigma^2 & 0 \\ 0 & 0 & 0 & 0 & \sigma^2 \end{pmatrix}$$

2.2 Heteroskedasticity

$$\begin{pmatrix} \sigma_1^2 & 0 & 0 & 0 & 0 \\ 0 & \sigma_2^2 & 0 & 0 & 0 \\ 0 & 0 & \sigma_3^2 & 0 & 0 \\ 0 & 0 & 0 & \sigma_4^2 & 0 \\ 0 & 0 & 0 & 0 & \sigma_5^2 \end{pmatrix}$$

2.3 General

$$\begin{pmatrix} \sigma_1^2 & \sigma_{12} & \sigma_{13} & \sigma_{14} & \sigma_{15} \\ \sigma_{12} & \sigma_2^2 & \sigma_{23} & \sigma_{24} & \sigma_{25} \\ \sigma_{13} & \sigma_{23} & \sigma_3^2 & \sigma_{34} & \sigma_{35} \\ \sigma_{14} & \sigma_{24} & \sigma_{34} & \sigma_4^2 & \sigma_{45} \\ \sigma_{15} & \sigma_{25} & \sigma_{35} & \sigma_{45} & \sigma_5^2 \end{pmatrix}$$

2.4 General Clustered (with G clusters)

$$\begin{pmatrix} \sigma_1^2 & \sigma_{12} & \sigma_{13} & \cdot & \cdot & 0 & 0 & 0 \\ \sigma_{12} & \sigma_2^2 & \sigma_{23} & \cdot & \cdot & 0 & 0 & 0 \\ \sigma_{13} & \sigma_{23} & \sigma_3^2 & \cdot & \cdot & 0 & 0 & 0 \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ 0 & 0 & 0 & \cdot & \cdot & \sigma_1^2 & \sigma_{12} & \sigma_{13} \\ 0 & 0 & 0 & \cdot & \cdot & \sigma_{12} & \sigma_2^2 & \sigma_{23} \\ 0 & 0 & 0 & \cdot & \cdot & \sigma_{13} & \sigma_{23} & \sigma_3^2 \end{pmatrix}$$

2.5 Random Effects Model

- Each cluster is structured as

$$\begin{pmatrix} \sigma^2 + \sigma_G^2 & \sigma_G^2 & \sigma_G^2 \\ \sigma_G^2 & \sigma^2 + \sigma_G^2 & \sigma_G^2 \\ \sigma_G^2 & \sigma_G^2 & \sigma^2 + \sigma_G^2 \end{pmatrix}$$

2.6 Clustered AR(1) Model

$$\begin{pmatrix} \sigma^2 & \rho\sigma^2 & \rho^2\sigma^2 & \cdot & \cdot & 0 & 0 & 0 \\ \rho\sigma^2 & \sigma^2 & \rho\sigma^2 & \cdot & \cdot & 0 & 0 & 0 \\ \rho^2\sigma^2 & \rho\sigma^2 & \sigma^2 & \cdot & \cdot & 0 & 0 & 0 \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ 0 & 0 & 0 & \cdot & \cdot & \sigma^2 & \rho\sigma^2 & \rho^2\sigma^2 \\ 0 & 0 & 0 & \cdot & \cdot & \rho\sigma^2 & \sigma^2 & \rho\sigma^2 \\ 0 & 0 & 0 & \cdot & \cdot & \rho^2\sigma^2 & \rho\sigma^2 & \sigma^2 \end{pmatrix}$$

3 Bias in Standard Errors with Non-Spherical Disturbances

- Model Outline: Assume
 - $Y = X\beta + \epsilon$
 - $V(X) = \sigma_X^2$
 - $V(\epsilon) = \sigma_\epsilon^2$
 - $Cov(X_{itg}, X_{isg}) = \rho_x$
 - $Cov(X_{itg}, X_{itg'}) = 0$
 - $Cov(\epsilon_{itg}, \epsilon_{isg}) = \rho_\epsilon$
 - $Cov(\epsilon_{itg}, \epsilon_{itg'}) = 0$
- OLS

$$\begin{aligned}
- \hat{\beta}_{OLS} &= (X'X)^{-1} X'Y \\
- SE(\hat{\beta}_{OLS}) &= (X'X)^{-1} (X'\Omega X) (X'X)^{-1}
\end{aligned}$$

• Note that

$$\begin{aligned}
- X'X &= \sum_{i=1}^N \sum_{t=1}^T x_{it}^2 \\
- X'\epsilon &= \sum_{i=1}^N \sum_{t=1}^T x_{it}\epsilon_{it}
\end{aligned}$$

– Since X is one dimensional vector, we get

$$\begin{aligned}
SE(\hat{\beta}_{OLS}) &= (X'X)^{-1} (X'\Omega X) (X'X)^{-1} \\
&= (X'X)^{-2} X'\Omega X
\end{aligned}$$

*

$$\begin{aligned}
\implies p \lim SE(\hat{\beta}_{OLS}) &= \\
&= \left(\sum_{i=1}^N \sum_{t=1}^T x_{it}^2 \right)^{-2} \left(\sum_{i=1}^N \sum_{t=1}^T x_{it}\epsilon_{it} \right)^2
\end{aligned}$$

$$= \frac{NT\sigma_X^2\sigma_\epsilon^2 + NT(T-1)\rho_X\rho_\epsilon}{(NT\sigma_X^2)^2}$$

$$= \frac{\sigma_\epsilon^2 + (T-1)\frac{\rho_X\rho_\epsilon}{\sigma_X^2}}{NT\sigma_X^2}$$

– Implications:

- * $\rho_x > 0, \rho_\epsilon > 0 \implies$ OLS standard errors downward biased: interpretation - some of the lack of variation is not independent
- * $\rho_x > 0, \rho_\epsilon < 0 \implies$ OLS standard errors upward biased: interpretation - some of the variation is not independent

4 Three Types of Fixes

- Keep $\hat{\beta}$ estimate and adjust standard errors.
 - Eicker-White heteroskedasticity robust standard errors
 - Cluster-Robust standard errors (called "clustering the standard errors")
 - Use complete variance-covariance matrix for inference
- Alter the estimator of $\hat{\beta}$ in addition to using non-OLS standard errors
 - GLS - Generalized Least Squares
 - FGLS - Feasible Generalized Least Squares
 - MLE - Maximum Likelihood
- Collapse data

5 General Tradeoff

- By imposing structure you get greater efficiency
 - Less parameters to estimate
 - More observations per parameter
- But you could be wrong about the structure in which case you could have the wrong standard errors

6 Eicker-White Heteroskedasticity Robust Standard Errors

- Heteroskedasticity robust standard errors keeps the OLS estimator but changes the standard errors by using the formula

$$V(\hat{\beta}_{OLS}) = (X'X)^{-1} X'\hat{\Omega}X (X'X)^{-1}$$

where $\hat{\Omega} =$

$$\begin{pmatrix} \hat{\epsilon}_1^2 & 0 & 0 & 0 & 0 \\ 0 & \hat{\epsilon}_2^2 & 0 & 0 & 0 \\ 0 & 0 & \hat{\epsilon}_3^2 & 0 & 0 \\ 0 & 0 & 0 & \hat{\epsilon}_4^2 & 0 \\ 0 & 0 & 0 & 0 & \hat{\epsilon}_5^2 \end{pmatrix}$$

- In other words:

$$V(\hat{\beta}_{OLS}) = \left(\sum_{i=1}^N x_i x_i' \right)^{-1} \left(\sum_{i=1}^N \hat{\epsilon}_i^2 x_i x_i' \right) \left(\sum_{i=1}^N x_i x_i' \right)^{-1}$$

- Note that the sample size for estimating σ_i^2 is one so that we do not have a consistent estimate of σ_i^2 .
- Tradeoff with GLS
 - Negative: Less efficient if truly heteroskedastic
 - Positive: Doesn't require knowledge of the variance-covariance matrix

7 Clustered Standard Errors

- When error terms are correlated within groups but not across groups and when the division of observations into groups is known, standard errors can be "clustered" or adjusted for within-group correlation.
- Clustered standard errors allow for arbitrary patterns of correlation within clusters (groups). Many clusters are needed to invoke asymptotic approximations (Donald and Lang, 2007).

7.1 Single Dimensional Clustering

Cluster-robust standard errors formula:

$$(X'X)^{-1} X'\hat{\Omega}X (X'X)^{-1}$$

where $\hat{\Omega} =$

$$\begin{pmatrix} \sigma_1^2 & \sigma_{12} & \sigma_{13} & \cdot & \cdot & 0 & 0 & 0 \\ \sigma_{12} & \sigma_2^2 & \sigma_{23} & \cdot & \cdot & 0 & 0 & 0 \\ \sigma_{13} & \sigma_{23} & \sigma_3^2 & \cdot & \cdot & 0 & 0 & 0 \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ 0 & 0 & 0 & \cdot & \cdot & \sigma_1^2 & \sigma_{12} & \sigma_{13} \\ 0 & 0 & 0 & \cdot & \cdot & \sigma_{12} & \sigma_2^2 & \sigma_{23} \\ 0 & 0 & 0 & \cdot & \cdot & \sigma_{13} & \sigma_{23} & \sigma_3^2 \end{pmatrix}$$

In other words:

$$V(\hat{\beta}_{OLS}) = \left(\sum_{c=1}^C X_c' X_c \right)^{-1} \sum_{c=1}^C X_c' \hat{\epsilon}_c \hat{\epsilon}_c' X_c \left(\sum_{c=1}^C X_c' X_c \right)^{-1}$$

7.2 Multi-Dimensional Clustering

- Suppose correlation exists in multiple dimensions within two dimensions of groups over time (i.e. within workers over time and across workers within a certain block of time)

- Two options:
 - Choose one dimension relevant to the parameter of interest and cluster only on one dimension
 - Cluster on two dimensions

- Assumptions

- $Y_{ijt} = X_{ijt}\beta + \epsilon_{ijt}$

- $cov(\epsilon_{ijt}, \epsilon_{kjt}) \neq 0$

- $cov(\epsilon_{ijt}, \epsilon_{imt}) \neq 0$

- $cov(\epsilon_{ijs}, \epsilon_{ijt}) = 0$

- So:

$$V(\hat{\beta}_{2D}) = (X'X)^{-1} \hat{Q} (X'X)^{-1}$$

where $\hat{Q} = X'(\hat{\Omega}S^{IJ})X$

- $S^{IJ} = S^I + S^J - S^{I \cap J}$ where S^K is the cluster matrix for dimension K

$$\begin{aligned} \hat{Q} &= X' (\hat{\epsilon}\hat{\epsilon}' S^{IJ}) X = \\ &X' (\hat{\epsilon}\hat{\epsilon}' S^I) X + X' (\hat{\epsilon}\hat{\epsilon}' S^J) X - \\ &X' (\hat{\epsilon}\hat{\epsilon}' S^{I \cap J}) X \end{aligned}$$

- A cluster matrix is a matrix of zeros and ones where a zero is entered if the entry in the variance-covariance matrix is assumed to be zero and a one is entered if the entry in the variance-covariance matrix is estimated. Example: Let S^I be given by (consecutive groupings):

$$\begin{pmatrix} 1 & 1 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \end{pmatrix}$$

– and S^J be given by (odd and even groupings):

$$\begin{pmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{pmatrix}$$

– Then, the intersection matrix enters a one if entries from both cluster matrices (S^I and S^J) are one and zero otherwise:

$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

• So $V(\hat{\beta}_{2D}) =$

$$\begin{aligned} & (X'X)^{-1} X' (\hat{\epsilon}\hat{\epsilon}' S^I) X (X'X)^{-1} + \\ & (X'X)^{-1} X' (\hat{\epsilon}\hat{\epsilon}' S^J) X (X'X)^{-1} - \\ & (X'X)^{-1} X' (\hat{\epsilon}\hat{\epsilon}' S^{I \cap J}) X (X'X)^{-1} \end{aligned}$$

- Thus, estimate 3 separate OLS regressions: one clustered by S^I , the next by S^J , and the third by $S^{I \cap J}$ and then compute the above formula.

8 Weighted Least Squares

- We now introduce estimators where we alter the estimation of β in addition to the standard errors. Why would we do this? Efficiency!

8.1 GLS

- Estimation
 - Variance-covariance matrix known: Ω

- Regress $\Omega^{-\frac{1}{2}}Y = \Omega^{-\frac{1}{2}}X\beta + \Omega^{-\frac{1}{2}}\mu$
- $\hat{\beta} = (X'\Omega X)^{-1} X'\Omega Y$
- Downweights high variance observations, upweights low variance observations
- Takes into account cross-observation correlation patterns

- Positive

- Can handle arbitrary correlation structures
- Efficient if you know the correlation structure

- Negative

- Relies on knowing the variance-covariance matrix Ω

- Weights efficiently so doesn't estimate average treatment effect in the presence of treatment effect heterogeneity

8.2 FGLS

- Estimation

- Stage 1: Run OLS - $Y = X\beta + \mu$
- Stage 2: extract variance-covariance matrix from stage 1 - $\hat{\Omega}$ and run GLS with estimated matrix:
Regress $\hat{\Omega}^{-\frac{1}{2}}Y = \hat{\Omega}^{-\frac{1}{2}}X\beta + \hat{\Omega}^{-\frac{1}{2}}\mu$
- $\hat{\beta} = (X'\hat{\Omega}X)^{-1} X'\hat{\Omega}Y$

- Positive

- Can handle arbitrary correlation structures

- Doesn't rely on knowing the variance-covariance matrix Ω

- Negative

- Biased in small samples: $E \left(X' \hat{\Omega} X \right)^{-1} X' \hat{\Omega} Y \neq \beta$
- Variance-covariance matrix noisy. Note that $\hat{\beta}_{FGLS}$ is consistent for β but $\hat{\Omega}$ is not consistent for Ω . To estimate, $\hat{\Omega}$, we need to estimate $\frac{N(N+1)}{2}$ entries of the variance-covariance matrix for a sample size of N
- Weights efficiently so doesn't estimate average treatment effect in the presence of treatment effect heterogeneity

9 Maximum Likelihood

- Can structurally model error terms - easy to allow for non-spherical disturbances
 - Note: not all distributions have an independent variance parameter - some like poisson, negative binomial, exponential have only one parameter. Others like the normal, lognormal have independent mean and variances.
- Benefits of MLE
 - Can have better small sample properties if you know the error term
 - Easier to model error structure
 - Reaches Cramer-Rao lower bound - efficient!
- Costs

- You need to know the distribution
- Not consistent if the distribution is wrong
- Can be biased in small samples even if the distribution is correct
- Doesn't generally have closed form computational formulas - have to solve simultaneously for set of first order conditions. Additional problems of knowing whether a solution to the set of first order conditions is a local/global maximum/minimum.

10 Structured FGLS:

10.1 Example - Cochrane-Orcutt

- Assume $Y_{it} = X_{it}\beta + \epsilon_{it}$ where $\epsilon_{it} = \rho\epsilon_{it-1} + \mu_{it}$

- Then follow these steps:

1. Estimate $Y_{it} = X_{it}\beta + \epsilon_{it}$

2. Regress $\epsilon_{it} = \rho\epsilon_{it-1} + \mu_{it}$ and obtain ρ

3. Then transform data to

$$Y_{it} - \rho Y_{it-1} = (X_{it} - \rho X_{it-1})\beta + \epsilon_{it}$$

4. $\hat{\beta}$ is now correct and so are the OLS standard errors

10.2 Example: Newey-West

- Variance covariance matrix with each cluster assumed to equal:

$$\begin{pmatrix} \sigma^2 & \left[1 - \frac{1}{M}\right] \sigma^2 & \cdot & \left[1 - \frac{K}{M}\right] \sigma^2 \\ \left[1 - \frac{1}{M}\right] \sigma^2 & \sigma^2 & \cdot & \left[1 - \frac{K-1}{M}\right] \sigma^2 \\ \left[1 - \frac{2}{M}\right] \sigma^2 & \left[1 - \frac{1}{M}\right] \sigma^2 & \cdot & \left[1 - \frac{K-2}{M}\right] \sigma^2 \\ \cdot & \cdot & \cdot & \cdot \\ \left[1 - \frac{K}{M}\right] \sigma^2 & \left[1 - \frac{K-1}{M}\right] \sigma^2 & \cdot & \sigma^2 \end{pmatrix}$$

- The above formulation, called the Newey-West estimator, allows for linear fall off in correlation of error terms within clusters
- Can be estimated using GLS or MLE

11 Collapsing

- Suppose that X variables are the same within cluster so that

$$Y_{ig} = \alpha + \beta X_g + C_g + \epsilon_{ig}$$

- Then there is no loss in collapsing the data because there is no within cluster variation used to identify β
- Otherwise you trade off:
 - Not using variation from a correlation structure you do not know
 - Throwing away useful correlation within clusters from covariates X